

1 SUMMARY

To **tabulate an integral function** of the form

$$g(x) = g(a) + \int_a^x f(t) dt$$

at points $x=a, a+h, \dots, a+mh$ to a **specified accuracy**.

The subroutine uses a variable step Simpson's rule using at each step an integration step, based on 4th differences, which is chosen small enough to achieve the required accuracy.

The user must specify a minimum integration step-size and provide a subroutine to evaluate the integrand $f(x)$.

ATTRIBUTES — **Version:** 1.0.0. **Types:** QA03A; QA03AD. **Calls:** CALCIN (a user subroutine). **Original date:** March 1963. **Origin:** M.J.D.Powell, Harwell.

2 HOW TO USE THE PACKAGE

2.1 The argument list

The single precision version

```
CALL QA03A(G, H, A, B, ACC, DXMIN)
```

The double precision version

```
CALL QA03AD(G, H, A, B, ACC, DXMIN)
```

G is a REAL (DOUBLE PRECISION in the D version) array into which the subroutine will put the values of $g(x)$ at the tabulation points. The user must set $G(1)$ to the value of $g(a)$ before calling the subroutine. The array must be at least of length $m+1$, see section 1 for a definition of m .

H is a REAL (DOUBLE PRECISION in the D version) variable which must be set by the user to h the interval of tabulation. **Restriction:** $h \leq \frac{1}{2}(b-a)$.

A is a REAL (DOUBLE PRECISION in the D version) variable which must be set by the user to a the first tabulation point.

B is a REAL (DOUBLE PRECISION in the D version) variable which must be set by the user to b the end of the range of tabulation.

ACC is a REAL variable which must be set by the user to the absolute accuracy required in the tabulated values of $g(x)$.

DXMIN is a REAL (DOUBLE PRECISION in the D version) variable which must be set by the user to the minimum step length to be used in the evaluation of the integral by Simpson's Rule. **Restriction:** $DXMIN < \frac{1}{3}h$.

This parameter may be used to limit the amount of time spent trying unsuccessfully to integrate an ill-defined $f(t)$. If trouble is not expected set **DXMIN** very small relative to h and **ACC**. Note: for each step of the integration the step size δx must approximately satisfy

$$ACC > \frac{\delta x^5}{90} |f^{(4)}(\xi)| \quad a \leq \xi \leq b$$

where $f^{(4)}(t)$ is the fourth derivative of $f(t)$. If the subroutine is unable to achieve the accuracy with a step length $\geq DXMIN$ a message is printed to that effect. In this event the array **G** will contain the values of $g(x)$ up to the

point of failure and the rest of the array will be set to zero.

2.2 The subroutine to evaluate $f(t)$

The user must provide a subroutine called `CALCIN` to calculate a value of $f(t)$ for any t in the range a to $a+mh$ where m equals the largest integer less than or equal to $(b-a)/h+\frac{1}{2}$. The subroutine must be of the form

```
SUBROUTINE CALCIN(T,F)
```

`T` is a REAL (DOUBLE PRECISION in the D version) variable which will contain on entry the value of t for the required $f(t)$.

`F` is a REAL (DOUBLE PRECISION in the D version) variable which `CALCIN` must set to the value of $f(t)$.

3 GENERAL INFORMATION

Use of common: None.

Workspace: None.

Other routines called directly: requires a user written subroutine called `CALCIN`.

Input/output: error message, see `DXMIN`.

4 METHOD

The integration is worked out by Simpson's Rule, the step length being chosen by the subroutine so that the specified accuracy is achieved in all tabulated values of $g(x)$. This step length is adjusted automatically by the subroutine for different parts of the range so that unnecessary values of $f(t)$ are not called for.