

## 1 SUMMARY

This subroutine **estimates the 1-norm** ( $\max_j \sum_{i=1}^n |a_{ij}|$ ) of an  $n \times n$  matrix  $\mathbf{A}$  given the ability to multiply a vector by both the matrix and its transpose. Because the explicit form of  $\mathbf{A}$  is not required, the subroutine can be used for estimating the norm of matrix functions such as the inverse. Additionally this subroutine is potentially useful for estimating condition numbers of a matrix when the matrix is sparse or not available explicitly.

**ATTRIBUTES** — **Version:** 1.0.0. (12 July 2004) **Types:** Real (single, double). **Calls:** I\_AMAX. **Original date:** June 2001. **Remark:** MC71 is a threadsafe version of MC41. **Origin:** M. Arioli, I.S. Duff, Harwell.

## 2 HOW TO USE THE PACKAGE

‘Reverse communication’ is used to provide the subroutine with the values of  $\mathbf{A}\mathbf{x}$  or  $\mathbf{A}^T\mathbf{x}$  for a given vector  $\mathbf{x}$ . When the subroutine requires the values of these products, it sets  $\mathbf{x}$  in the array X and returns to the user’s program with a flag, called KASE, set to 1 if  $\mathbf{A}\mathbf{x}$  is required or set to 2 if  $\mathbf{A}^T\mathbf{x}$  is required. The user’s program must set X to the value of the matrix-vector product required by the subroutine and it must not alter the value of any other arguments of the subroutine. Initially the user must set the value of KASE to 0; the subroutine sets KASE to 0 at the end of the computation. An example of use is shown in Section 5.

### 2.1 Argument list

*The single precision version:*

```
CALL MC71A(N,KASE,X,EST,W,IW,KEEP)
```

*The double precision version:*

```
CALL MC71AD(N,KASE,X,EST,W,IW,KEEP)
```

**N** is an INTEGER variable that must be set by the user to the order of the matrix. This argument is not altered by the subroutine. **Restriction:**  $N > 0$ .

**KASE** is an INTEGER variable that must be set by the user to 0 on the initial call. The subroutine sets KASE to 1 or 2 in the intermediate returns and to 0 for the final return.  $KASE = -1$  indicates an error condition (see §2.5).

When  $KASE = 1$  the user must supply the product of X by the matrix  $\mathbf{A}$ .

When  $KASE = 2$  the user must supply the product of X by the transpose of the matrix  $\mathbf{A}$ .

**X** is a REAL (DOUBLE PRECISION in the D version) array of length N that need not be set by the user initially. In the intermediate returns, X must be overwritten by the product of the output value of X by the matrix ( $KASE = 1$ ) or by the transpose of the matrix ( $KASE = 2$ ).

**EST** is a REAL (DOUBLE PRECISION in the D version) variable. It is set by the subroutine to contain a lower bound estimate for the 1-norm of the matrix.

**W** is a REAL (DOUBLE PRECISION in the D version) array of length N that is used by the routine as private workspace and must not be altered by the user.

**IW** is an INTEGER array of length N that is used by the routine as private workspace and must not be altered by the user.

**KEEP** is an INTEGER array of length 5 which is used by the routine as private workspace and must not be altered by the user.

## 2.2 Finding the $\infty$ -norm

Since  $\|\mathbf{B}\|_\infty = \|\mathbf{B}^T\|_1$ , the subroutine can be used to estimate the  $\infty$ -norm of  $\mathbf{B}$  by working with  $\mathbf{A} = \mathbf{B}^T$ .

## 2.3 Finding condition numbers

The subroutine can be used to estimate the classical condition number  $\kappa(\mathbf{B}) = \|\mathbf{B}\| \|\mathbf{B}^{-1}\|$  (for either 1 or  $\infty$ -norm) of a matrix  $\mathbf{B}$  assuming it is possible to solve both the systems  $\mathbf{B}\mathbf{y} = \mathbf{x}$  and  $\mathbf{B}^T\mathbf{y} = \mathbf{x}$  for different right-hand sides  $\mathbf{x}$ . The products of  $\mathbf{A} = \mathbf{B}^{-1}$  or  $\mathbf{A}^T = \mathbf{B}^{-T}$  times a given vector  $\mathbf{x}$  can be computed by solving the corresponding systems.

## 2.4 Nonsquare matrices

It is also possible to use MC71 for computing the 1-norm or the  $\infty$ -norm of an  $m \times n$  matrix  $\mathbf{B}$ . This can be easily calculated by computing the norm of the square matrix obtained by bordering the matrix  $\mathbf{B}$  with  $(m-n)$  zero columns if  $m > n$  or with  $(n-m)$  zero rows if  $m < n$ .

## 2.5 Errors and diagnostic messages

The value  $-1$  for KASE indicates that  $N \leq 0$ .

## 3 GENERAL INFORMATION

**Workspace:** Provided by user, see arguments IW and W.

**Use of common:** None.

**Other routines called directly:** MC71A/AD calls I\_AMAX. The user does not need to call these subroutines directly.

**Input/output:** None.

**Restrictions:**  $N > 0$ .

## 4 METHOD

The method used is based on that developed by Hager (1984) and incorporates the modifications suggested by Higham (1987). Because  $\|\mathbf{A}\|_1$  is the global maximum of the function  $f(\mathbf{x}) = \|\mathbf{A}\mathbf{x}\|_1$  over the set  $S = \{\mathbf{x} : \|\mathbf{x}\|_1 \leq 1\}$ , Hager (1984) introduces an iterative method which, at each step, moves from a point in  $S$  to another one where the value of  $f(\mathbf{x})$  increases. In a finite number of iterations ( $\leq n$ ) the algorithm guarantees the convergence to a local maximum of  $f(\mathbf{x})$ . In practice, 2 or 3 iterations are sufficient to obtain a local maximum. In MC71A/AD, the number of iterations is limited to 5. Each iteration requires one matrix-vector product of the form  $\mathbf{A}\mathbf{x}$  and one of the form  $\mathbf{A}^T\mathbf{x}$  so the maximum number of calls to MC71A/AD that the user need make is 12.

MC71A/AD does not require the user to supply the matrix  $\mathbf{A}$  but does require the user to compute products  $\mathbf{A}\mathbf{x}$  and  $\mathbf{A}^T\mathbf{x}$ . Hence, it is possible to use MC71A/AD to compute the norm of a matrix which is a function of matrices without computing the resulting matrix explicitly. For example, the norm of the inverse of a matrix  $\mathbf{B}$  may be estimated if the systems  $\mathbf{B}\mathbf{y} = \mathbf{x}$  and  $\mathbf{B}^T\mathbf{y} = \mathbf{x}$  can be solved. Arioli, Demmel, and Duff (1988) use this method for estimating different kinds of condition numbers of a sparse matrix.

## References

Arioli, M., Demmel J.W., and Duff, I.S. (1988). Solving sparse systems with sparse backward error. Report CSS 214, CSS Division, Harwell Laboratory, England.

Hager, W.W. (1984). Condition Estimates. *SIAM J. Sci. Stat. Comput.* **5**, 311-316.

Higham, N.J. (1987). Fortran codes for estimating the 1-norm of a real or complex matrix, with applications to condition estimation. Numerical Analysis Report 135, University of Manchester M13 9PL, England.

## 5 EXAMPLE OF USE

The following example shows the use of the subroutine MC71AD for computing the  $\infty$ -norm of the matrix

$$\mathbf{A} = \begin{pmatrix} 1 & -2 & 1 & -2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}.$$

When the program of Figure 1 is run on the input

```
4
1.0 -2.0 1.0 -2.0
0.0 1.0 0.0 0.0
0.0 0.0 1.0 0.0
1.0 0.0 0.0 1.0
```

it produces the output

```
ESTIMATE OF THE NORM OF THE MATRIX 0.6000D+01
```

```

      DOUBLE PRECISION A(10,10), W(10), X(10), V(10), EST
      INTEGER IW(10),KEEP(5)
      INTEGER N,I,J,LA,KASE,ITER,ITYPE
      READ(5,10) N
      READ(5,20) ((A(I,J),J=1,N),I=1,N)
10    FORMAT(I3)
20    FORMAT(4F5.1)
C
      LA = 10
      KASE = 0
      DO 100 ITER = 1,12
          CALL MC71AD(N,KASE,X,EST,V,IW,KEEP)
          IF (KASE .LT. 0) GO TO 600
          IF (KASE .EQ. 0) GO TO 200
          ITYPE = 2 * KASE - 3
          CALL MAPX(LA, N, A, X, W, ITYPE)
100    CONTINUE
200    WRITE(6,9998) EST
      GO TO 1000
600    WRITE(6,9997)
1000   STOP
9997   FORMAT(' MC71AD- N .LE. 0 ')
9998   FORMAT(' ESTIMATE OF THE NORM OF THE MATRIX ',E10.4)
      END
      SUBROUTINE MAPX(LA, N, A, X, W, ITYPE)
      INTEGER LA,N,ITYPE,I,J
      DOUBLE PRECISION A(LA,LA), X(N), W(N), ZERO
      DATA ZERO /0.0D0/
      IF (ITYPE .EQ. 1) THEN
          DO 100 I = 1,N
              W(I) = ZERO
              DO 200 J = 1,N
                  W(I) = W(I) + A(I,J) * X(J)
200          CONTINUE
100     CONTINUE
      ELSE
          DO 300 I = 1,N
              W(I) = ZERO
              DO 400 J = 1,N
                  W(I) = W(I) + A(J,I) * X(J)
400     CONTINUE
300     CONTINUE
      ENDIF
      DO 500 I = 1,N
          X(I) = W(I)
500    CONTINUE
      RETURN
      END

```

Figure 1. Code to estimate the infinity norm of a matrix